

F 415 – Mecânica Geral II

1º semestre de 2024

19/03/2024

Aula 5

Aulas passadas

Conservação do momento angular interno: $\ell = \mu r^2 \dot{\theta} = \text{const.}$

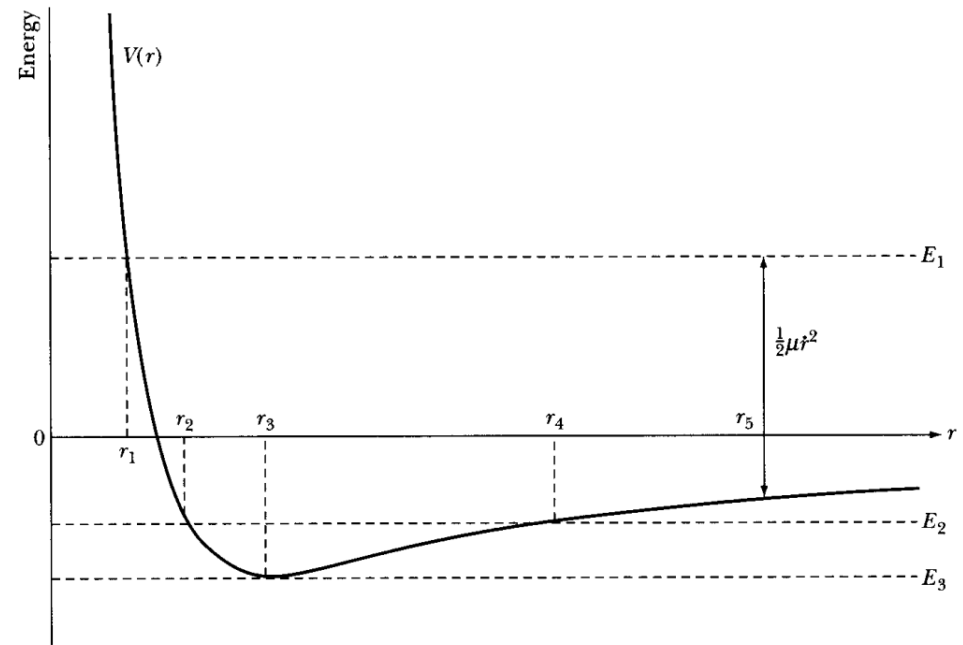
Conservação da energia mecânica total:

$$E = \frac{\mu}{2} \dot{r}^2 + \frac{\mu}{2} r^2 \dot{\theta}^2 + U(r) = \text{const.}$$

$$E = \frac{\mu}{2} \dot{r}^2 + \frac{\ell^2}{2\mu r^2} + U(r) = \text{const.}$$

Potencial efetivo:

$$V(r) = \frac{\ell^2}{2\mu r^2} + U(r) \Rightarrow \text{pontos de retorno}$$



Equação da trajetória: $u(\theta) \equiv \frac{1}{r(\theta)} \Rightarrow \frac{d^2 u}{d\theta^2} + u = -\frac{\mu}{\ell^2 u^2} F\left(\frac{1}{u}\right)$

Aula passada

Problema de Kepler:

$$k = GMm$$

$$U(r) = -\frac{k}{r} \Rightarrow r(\theta) = \frac{\alpha}{1 + \varepsilon \cos \theta}$$

$$\alpha = \frac{\ell^2}{\mu k}$$

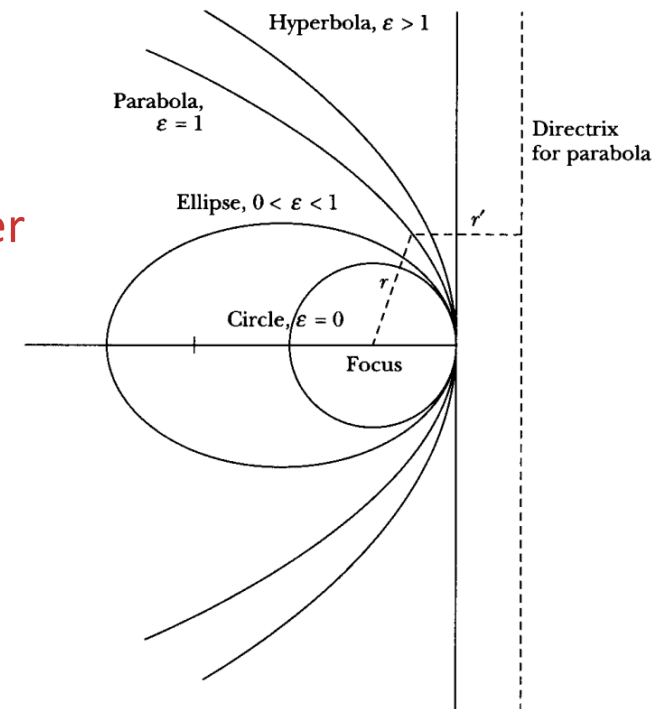
$$\varepsilon = \sqrt{1 + \frac{2\ell^2 E}{\mu k^2}} = \sqrt{1 - \frac{E}{V_{min}}}$$

$$E = V_{min} \Rightarrow \varepsilon = 0 \Rightarrow \text{círculo}$$

$$V_{min} < E < 0 \Rightarrow 0 < \varepsilon < 1 \Rightarrow \text{elipse } 1^{\text{a}} \text{ lei de Kepler}$$

$$E = 0 \Rightarrow \varepsilon = 1 \Rightarrow \text{parábola}$$

$$E > 0 \Rightarrow \varepsilon > 1 \Rightarrow \text{hipérbole}$$



Aula passada

$$r_{min} = \frac{\alpha}{1 + \varepsilon} \quad (\theta = 0)$$

$$r_{max} = \frac{\alpha}{1 - \varepsilon} \quad (\theta = \pi)$$

$$r_{max} + r_{min} = 2a$$

$$r_{max} - r_{min} = 2c = 2\varepsilon a$$

$$a = \frac{\alpha}{1 - \varepsilon^2} = \frac{k}{2|E|} \Rightarrow E = -\frac{k}{2a}$$

$$b = \sqrt{1 - \varepsilon^2} a = \frac{\alpha}{\sqrt{1 - \varepsilon^2}} = \frac{\ell}{\sqrt{2\mu|E|}}$$

Terceira lei de Kepler: $\frac{T^2}{a^3} = 4\pi^2 \frac{\mu}{k} = \frac{4\pi^2}{G(m_1 + m_2)} \xrightarrow{m_2 \gg m_1} \frac{4\pi^2}{Gm_2}$

Potencial $1/r$ repulsivo

$$U(r) = \frac{k}{r} \quad (k > 0) \Rightarrow F(r) = -\frac{dU}{dr} = \frac{k}{r^2}$$

$$V(r) = \frac{l^2}{2\mu r^2} + \frac{k}{r} > 0$$

$$\frac{d^2 u}{d\theta^2} + u = -\frac{\mu k}{l^2}$$

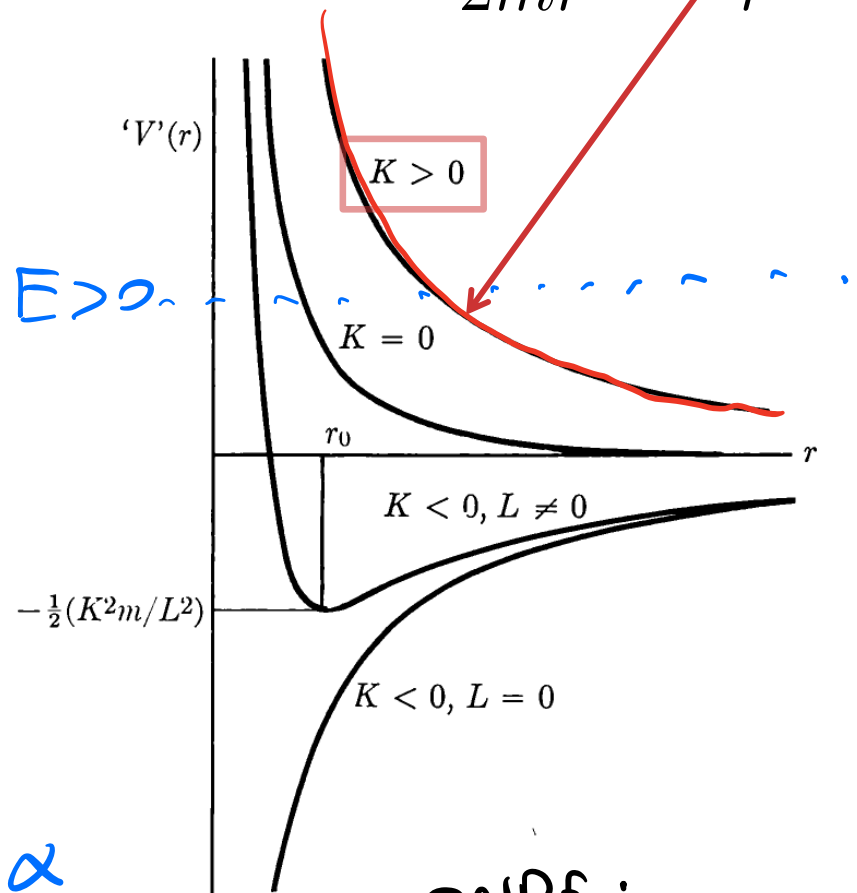
$$u(\theta) = A \cos(\theta - \theta_0) - \frac{\mu k}{l^2}$$

$$\theta_0 = 0 \quad E > 0 \quad A > 0$$

$$u(\theta) = A \cos(\theta) - \frac{\mu k}{l^2} = \frac{1}{r(\theta)}$$

$$r(\theta) = \frac{1}{A \cos \theta - \frac{\mu k}{l^2}} = \frac{l^2 / \mu k}{\epsilon \cos \theta - 1} \quad \alpha$$

$$V(r) = \frac{L^2}{2mr^2} + \frac{K}{r}$$



ONDE:

$$\epsilon = \frac{A l^2}{\mu k}$$

Equação da trajetória

$$r(\theta) = \frac{\alpha}{\Sigma \cos \theta - 1}$$

PARA QUE HAJA CURVA:

$$\Sigma > 1$$

DO CONTRÁRIO: $\Sigma \cos \theta - 1 < 0 \Rightarrow r < 0$

Potencial $1/r$ repulsivo

O caso atrativo é o ramo (+) da hipérbole

$$U(r) = \frac{k}{r} \Rightarrow r(\theta) = \frac{\alpha}{-1 + \varepsilon \cos \theta}$$

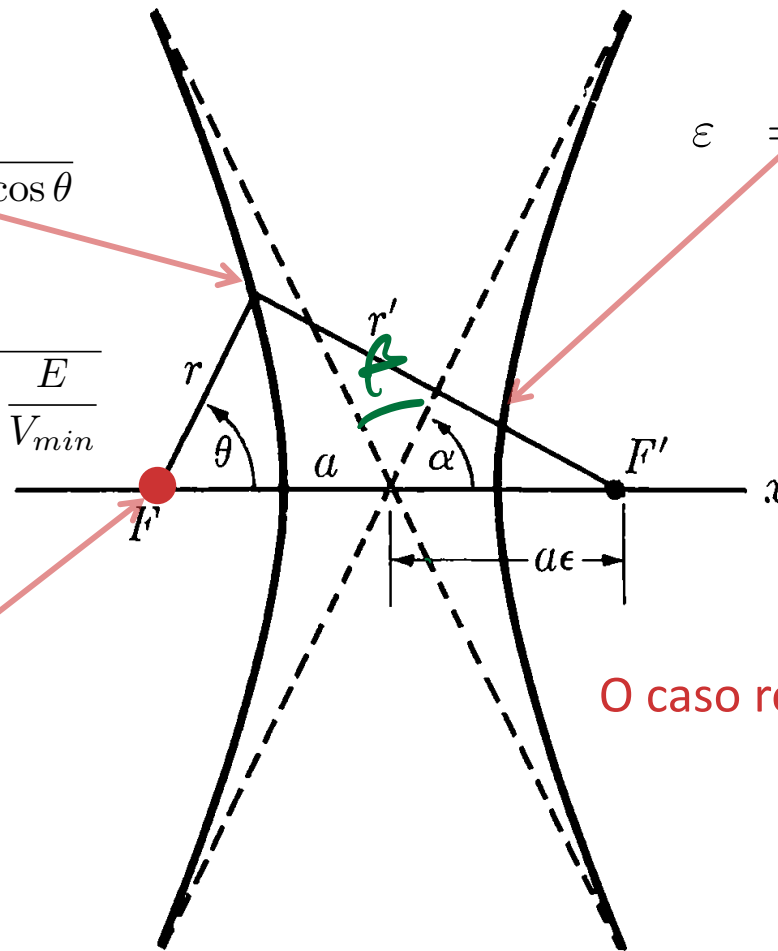
$$\alpha = \frac{\ell^2}{\mu k}$$

$$\varepsilon = \sqrt{1 + \frac{2\ell^2 E}{\mu k^2}} \quad (E > 0)$$

$$U(r) = -\frac{k}{r} \Rightarrow r(\theta) = \frac{\alpha}{1 + \varepsilon \cos \theta}$$

$$\alpha = \frac{\ell^2}{\mu k}$$

$$\varepsilon = \sqrt{1 + \frac{2\ell^2 E}{\mu k^2}} = \sqrt{1 - \frac{E}{V_{min}}}$$



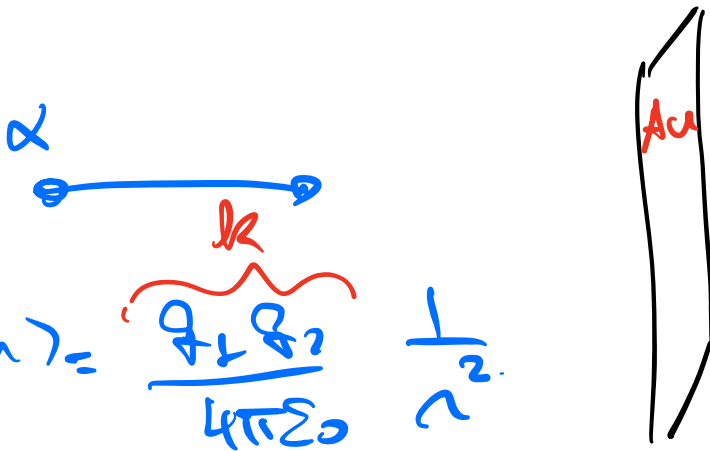
centro de força

O caso repulsivo é o ramo (-) da hipérbole

+branch

-branch

Espalhamento de Rutherford



$$F(r) = \frac{q_1 q_2}{4\pi\epsilon_0} \frac{1}{r^2}$$

$$U(r) = \frac{k}{r}$$

A ÚNICA QUANTIDADE RELEVANTE PARA

NÓS É O DESVIO DA TRAJETÓRIA INICIAL.

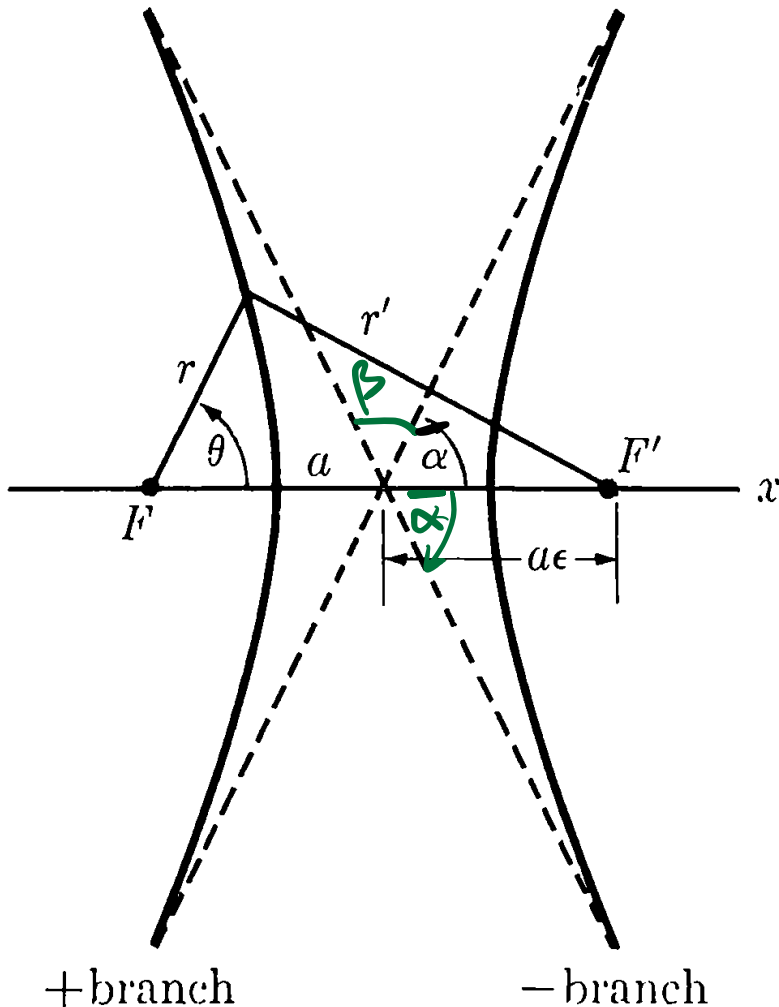


α = NÚCLEO DO He
 = 2 p's + 2 n's

Au \Rightarrow Z = 79

$M_{Au} = 197$ u.m.a.

Os ângulos assintóticos



$$r(\theta) = \frac{a}{\epsilon \cos \theta - 1}$$

$$\bar{\alpha} = ?$$

$\bar{\alpha}$ CORRESPONDE AO
ÂNGULO ONDE $r(\theta \rightarrow \bar{\alpha}) \rightarrow \infty$

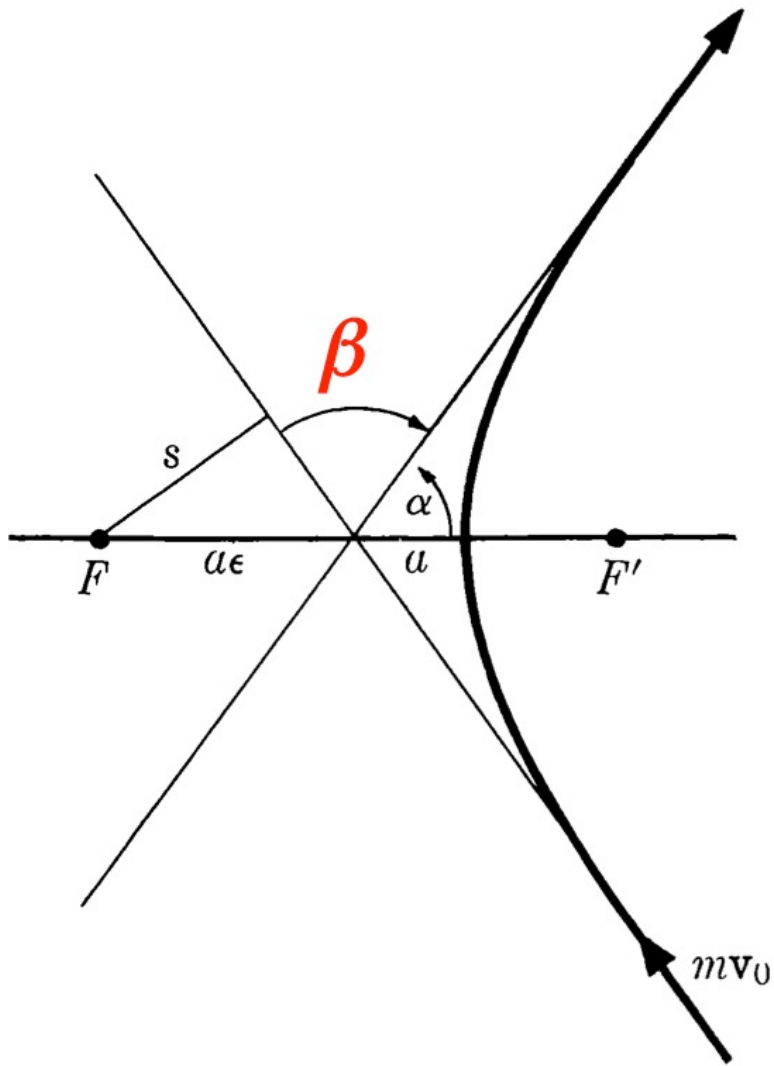
$$\Rightarrow \epsilon \cos \bar{\alpha} - 1 = 0$$

$$\Rightarrow \cos \bar{\alpha} = \frac{1}{\epsilon}$$

$$\Rightarrow \beta = \pi - 2\bar{\alpha}$$

$$\tan\left(\frac{\beta}{2}\right) = \tan\left(\frac{\pi}{2} - \bar{\alpha}\right) = \cot \bar{\alpha}$$

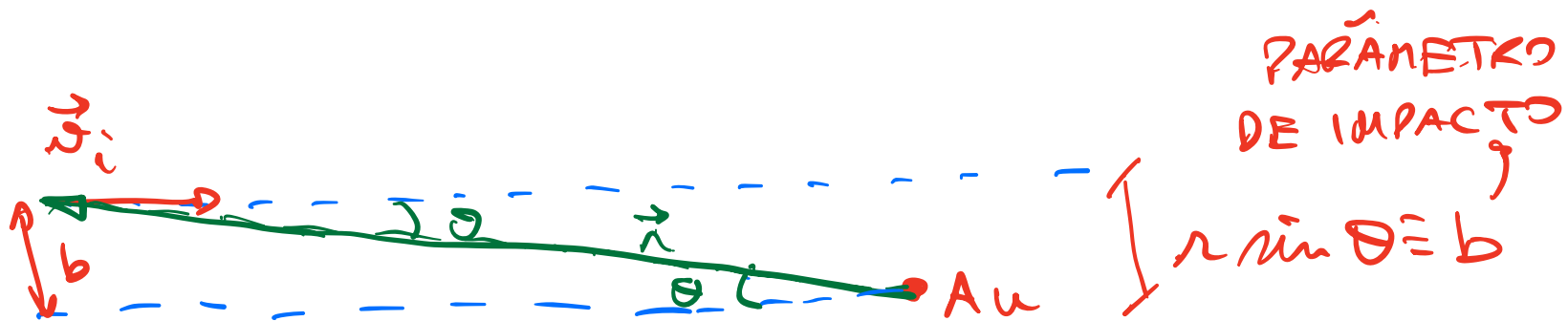
A deflexão total β



$$\tan \frac{\beta}{2} = \cot \alpha$$

$$\Rightarrow \tan \frac{\beta}{2} = \frac{1}{\sqrt{\epsilon^2 - 1}}$$

$$\tan \frac{\beta}{2} = \sqrt{\frac{\ell k^2}{2\ell^2 E}}$$

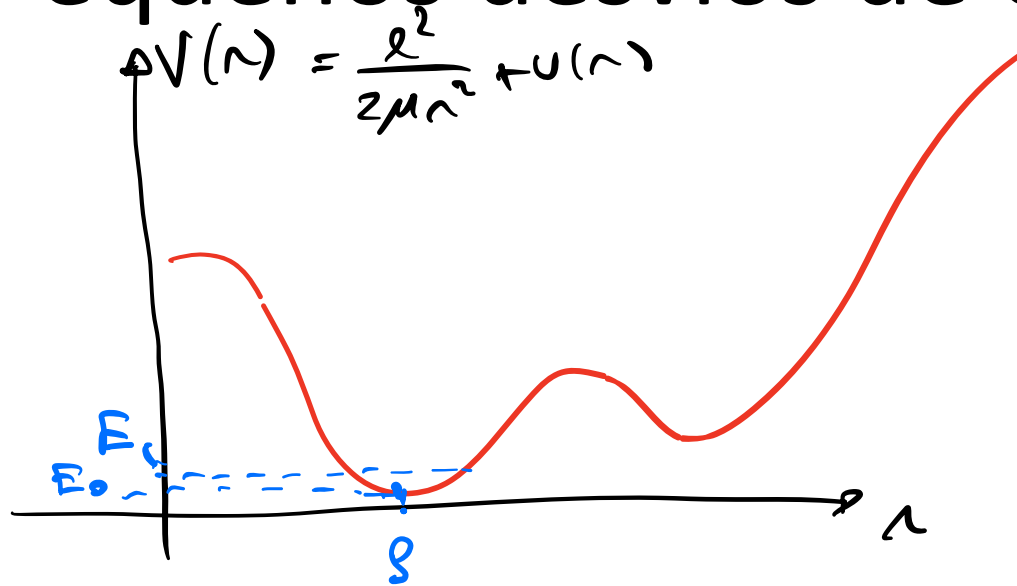


$$E = T + U(r) = \frac{\mu}{2} v^2 + \frac{k}{r} \xrightarrow{r \rightarrow \infty} E = \frac{\mu}{2} v^2 = \frac{\mu}{2} v_i^2$$

$$l = ? \quad l = |\mu \vec{r} \times \vec{v}| = \mu r v \sin \theta = \mu v b$$

$$\Rightarrow \tan\left(\frac{\theta}{2}\right) = \frac{k}{\mu b v_i^2}$$

Pequenos desvios de órbitas circulares



SE $E = E_0$: $r = \rho = \text{const}$

$\dot{\theta} = \frac{l}{\mu r^2} = \frac{l}{\mu \rho^2} = \text{const.}$

⇒ MCV

SE $E = E_1 \Rightarrow r \in [\rho - \epsilon, \rho + \epsilon]$, PODEMOS SUBSTITUIR O POTENCIAL EXATO POR UMA PARÁBOLA:

$\Rightarrow V(r) \cong V(\rho) + \frac{dV}{dr} \Big|_{r=\rho} (r-\rho) + \frac{1}{2} \frac{d^2V}{dr^2} \Big|_{r=\rho} (r-\rho)^2$

$V(r) \cong \text{const.} + \frac{1}{2} k (r-\rho)^2$

$k = \frac{d^2V}{dr^2} \Big|_{r=\rho} > 0$

$-\frac{dV}{dr} = -k(r-\rho)$

mínimo

$$\mu \ddot{n} = -\frac{dV}{dn} = -k(n-s)$$

DEFININDO: $x = n - s \Rightarrow \ddot{x} = \ddot{n} \Rightarrow \boxed{\mu \ddot{x} + kx = 0}$

$$x(t) = A \cos(\omega t + \delta) \quad \omega = \sqrt{\frac{k}{\mu}} = \sqrt{\frac{V''(s)}{\mu}}$$

$$n(t) = s + A \cos(\omega t + \delta)$$

TRAJETÓRIAS SERÃO FECHADAS SE

$$\frac{\omega}{\dot{\theta}} = \frac{p}{q} \quad p, q \in \mathbb{N}^+$$

$$\dot{\theta} = \frac{L}{\mu r^2} \approx \frac{L}{\mu s^2}$$

$$\frac{\sqrt{\frac{V''(s)}{\mu}}}{L/\mu s^2} \stackrel{?}{=} \frac{p}{q}$$

EXEMPLO (VER NOTAS)

$$V(r) = -\frac{k}{r^m}$$

$$V(r) = \frac{l^2}{2\mu r^2} - \frac{k}{r^m}$$

$$\frac{dV}{dr} \Big|_{r=s} = 0$$

$$g^{(m-2)} = \frac{\mu k e}{l^2}$$

$$\frac{d^2V}{dr^2} \Big|_{r=s} > 0 \Rightarrow \boxed{m < 2}$$

$$\omega = \frac{l}{\mu s^2} \sqrt{2-m} = \sqrt{\frac{V''(s)}{\mu}}$$

$$\frac{\omega}{\dot{\theta}} = \sqrt{2-m} = \begin{cases} m=1: \Delta = \text{FECHADA (KEPLER)} \\ m=-2: (k < 0) \quad 2 \Rightarrow \text{FECHADA (OH3D)} \\ \cancel{m=-7} \quad (\text{INDA ALÉM DE } (r-s)^2) \end{cases}$$

Cap. 9

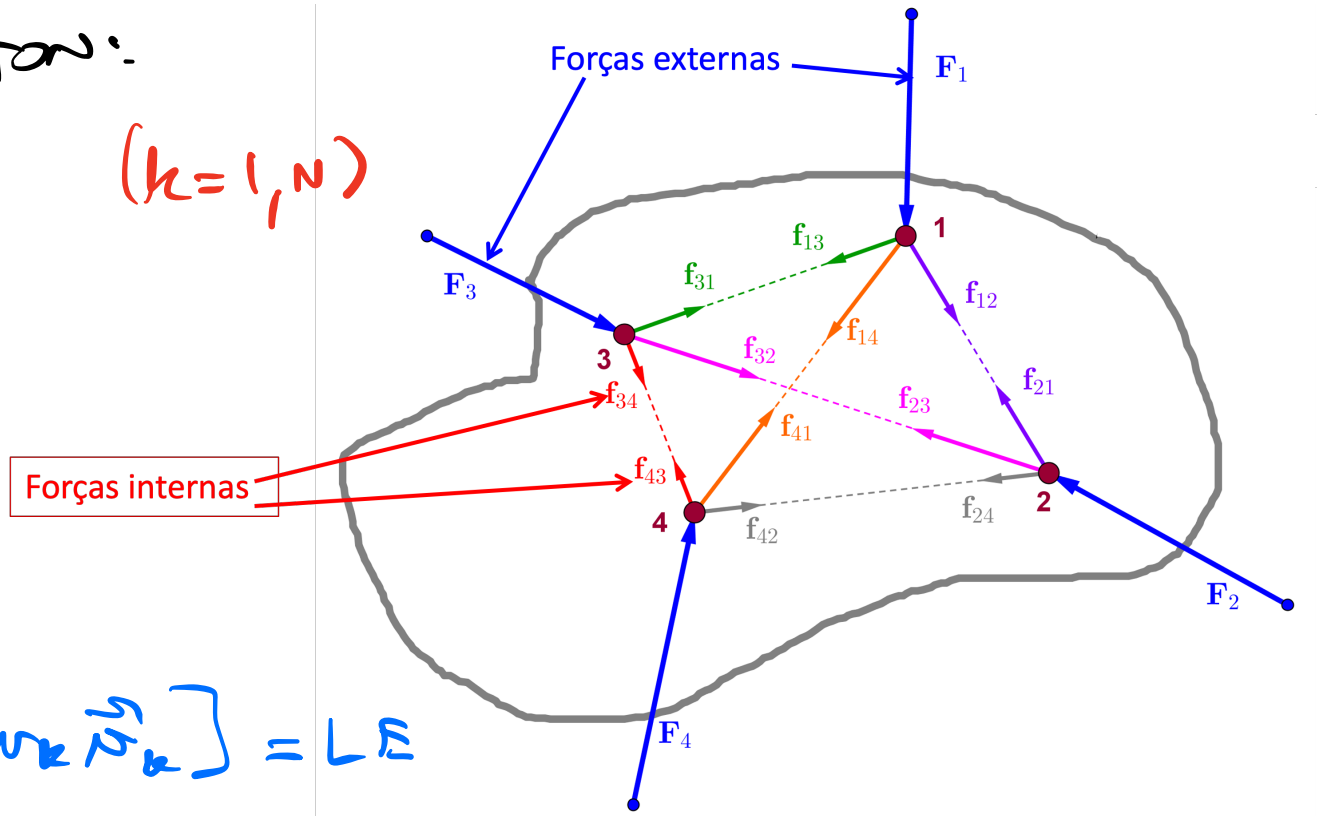
Dinâmica de um sistema de muitas partículas

Leis de conservação: momento linear

2ª LEI DE NEWTON:

$$m_k \frac{d^2 \vec{r}_k}{dt^2} = \vec{F}_k + \vec{f}_k \quad (k=1, N)$$

$$\vec{f}_k = \sum_{\substack{j=1 \\ j \neq k}}^N \vec{f}_{kj}$$



$$\frac{d}{dt} \left[m_k \frac{d \vec{r}_k}{dt} \right] = \frac{d}{dt} \left[m_k \vec{v}_k \right] = LE$$

SOMO SOBRE k :

$$LE = \sum_{k=1}^N \frac{d}{dt} \left[m_k \vec{v}_k \right] = \frac{d}{dt} \left[\sum_k \overbrace{m_k \vec{v}_k}^{\vec{p}_k} \right] = \frac{d}{dt} \left[\sum_k \vec{p}_k \right]$$

$$= \frac{d}{dt} \vec{P}$$

ONDE

$$\vec{P} = \sum_k \vec{p}_k = \text{MOM. LINEAR TOTAL}$$

$$\frac{d\vec{p}}{dt} = \underbrace{\sum_k \vec{T}_k}_{\vec{T}} + \underbrace{\sum_k \vec{f}_k}_{\vec{T}} \Rightarrow \boxed{\frac{d\vec{p}}{dt} = \vec{T}}$$

\vec{T} = FORÇA EXTERNA TOTAL

$$\sum_k \vec{f}_k = \sum_k \sum_{\substack{j \neq k \\ j \neq \text{center}}} \vec{f}_{kj} = 0$$

$N=4$:

$k=1$:

~~$f_{12} + f_{13} + f_{14}$~~

$k=2$:

~~$f_{21} + f_{23} + f_{24}$~~

$k=3$:

~~$f_{31} + f_{32} + f_{34}$~~

$k=4$:

~~$f_{41} + f_{42} + f_{43}$~~

3ª LEI DE

NEWTON

$$\frac{d\vec{p}}{dt} = \vec{F}$$

$$\text{SE } \vec{F} = 0 \Rightarrow \vec{p} = \text{CONST.}$$

LEI DE CONSERVAÇÃO DO MOMENTO
LINEAR TOTAL DE UM SISTEMA
DE N PARTÍCULAS.