

$$6) \quad V(r) = \begin{cases} -V_0 & 0 < r < a \\ 0 & r > a \end{cases}$$

a) EQ. RADIAL ($l=0$) ESTADOS LIGADOS ($E < 0$)

$$\left[-\frac{\hbar^2}{2\mu} \frac{d^2}{dr^2} + V(r) \right] u_{k,0}(r) = E u_{k,0}(r)$$

COND. CONTORNO (COMO EM 1D):

$$u_{k,0}(r) \text{ CONTÍNUA EM } r=a$$

$$u'_{k,0}(r) \quad " \quad " \quad "$$

$$r < a: \quad V(r) = -V_0$$

$$+\frac{\hbar^2}{2\mu} u''_{k,0}(r) + \overbrace{(V_0 + E)}^{> 0} u_{k,0}(r) = 0$$

$$u_{k,0}(r) = A \sin kr + \cancel{B} \cos kr \quad (r < a)$$

$$u''_{k,0}(r) = -k^2 [A \sin kr + B \cos kr]$$

$$-\frac{\hbar^2 k^2}{2\mu} = -(V_0 + E) \Rightarrow k = \sqrt{\frac{2(V_0 + E)\mu}{\hbar^2}}$$

$$u_{k,0}(r) \xrightarrow{r \rightarrow 0} r^{(l+1)} = r \Rightarrow B = 0$$

$$r > a \quad V(r) = 0$$

$$+\frac{\hbar^2}{2\mu} u_{k,0}''(r) + E u_{k,0}(r) = 0 \quad E < 0$$

$$u_{k,0}(r) = C e^{-Kr} + \cancel{D e^{+Kr}} \quad K = \frac{\sqrt{-2\mu E}}{\hbar}$$

COND. CONTORNO ($r \rightarrow \infty$)

$$u_{k,0}(r) \xrightarrow{r \rightarrow \infty} 0 \Rightarrow D = 0$$

$$u_{k,0}(r) = C e^{-Kr} \quad (r > a)$$

b) CASAR AS SOLUÇÕES EM $r=0$:

$u_{k,0}(r)$ CONTÍNUA EM $r=0$:

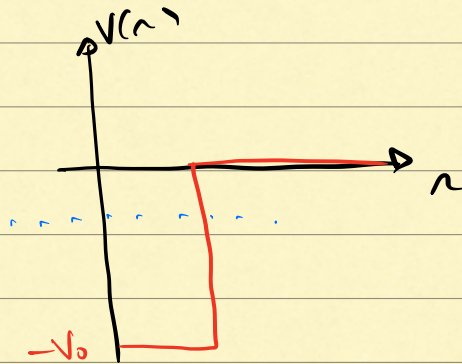
$$A \sin(ka) = C e^{-ka} \quad (1)$$

$u_{k,0}'(r)$ CONTÍNUA EM $r=0$:

$$+kA \cos(ka) = -CK e^{-ka} \quad (2)$$

$$(1) \div (2) \Rightarrow \frac{\tan(ka)}{k} = -\frac{1}{K} \Rightarrow \tan(ka) = -\frac{k}{K}$$

c) MÍNIMO DE V_0 PARA QUE HAJA UM ESTADO LIGADO



SE V_0 FOR DIMINUINDO CHEGARÁ UM MOMENTO EM QUE O ÚLTIMO ESTADO LIGADO DESAPARECERÁ

CONDIÇÃO PARA O $V_{0c} \Rightarrow E=0$

$$\tan(ka) = -\frac{k}{K}$$

$$K = \frac{\sqrt{2\mu|E|}}{\hbar} \xrightarrow{V_0 \rightarrow V_{0c}} 0$$

$$\frac{k}{K} \xrightarrow{V_0 \rightarrow V_{0c}} \infty$$

$$K = \frac{\sqrt{2\mu(E+V_0)}}{\hbar}$$

$$ka \rightarrow (2m+1)\frac{\pi}{2}$$

$$\xrightarrow{V_0 \rightarrow V_{0c}} \frac{\sqrt{2\mu V_{0c}}}{\hbar}$$

$$\frac{\sqrt{2\mu V_{0c}}}{\hbar} a \rightarrow (2m+1)\frac{\pi}{2}$$

$$\text{MENOR } V_{0c} \Rightarrow m=0 \Rightarrow \sqrt{2\mu V_{0c}} = \frac{\pi \hbar}{2a}$$

$$\Rightarrow V_{0c} = \frac{\pi^2 \hbar^2}{8\mu a^2}$$

a) DÊUTERON : ESTADO LIGADO DE UM p E UM n

$$\mu = \frac{m_p m_n}{m_p + m_n} \approx \frac{m_p}{2}$$

$$V_0 \approx \frac{\pi^2 \hbar^2}{8\mu a^2} = \frac{\pi^2 \hbar^2}{4m_p a^2} \sim 26 \text{ MeV}$$

$$m_p c^2 \sim 980 \text{ MeV}$$

5) $V(\rho)$ SIMETRIA CILÍNDRICA

\Rightarrow COORD. CILÍNDRICAS (ρ, ϕ, z)

$$a) H = \frac{\hbar^2 \nabla^2}{2\mu} + V(\rho)$$

$$\nabla^2 = \frac{\partial^2}{\partial \rho^2} + \frac{1}{\rho} \frac{\partial}{\partial \rho} + \frac{1}{\rho^2} \frac{\partial^2}{\partial \phi^2} + \frac{\partial^2}{\partial z^2}$$

$$H \rightarrow \left[\frac{\hbar^2}{2\mu} \left(\frac{\partial^2}{\partial \rho^2} + \frac{1}{\rho} \frac{\partial}{\partial \rho} + \frac{1}{\rho^2} \frac{\partial^2}{\partial \phi^2} + \frac{\partial^2}{\partial z^2} \right) + V(\rho) \right]$$

MOSTRE: $[H, L_z] = [H, P_z] = 0$

$$L_z = \frac{\hbar}{i} \frac{\partial}{\partial \phi}$$

$$P_z = \frac{\hbar}{i} \frac{\partial}{\partial z}$$

COMO V SO' DEPENDE DE ρ : $[L_z, V(\rho)] = [P_z, V(\rho)] = 0$

$$[L_z, T] = \left[\frac{\hbar}{i} \frac{\partial}{\partial \phi}, -\frac{\hbar^2}{2\mu} \left(\frac{\partial^2}{\partial \rho^2} + \frac{1}{\rho} \frac{\partial}{\partial \rho} + \frac{1}{\rho^2} \frac{\partial^2}{\partial \phi^2} + \frac{\partial^2}{\partial z^2} \right) \right]$$

$$\left[\frac{\partial}{\partial \phi}, \frac{\partial^2}{\partial \rho^2} \right] = 0 = \left[\frac{\partial}{\partial \phi}, \frac{1}{\rho} \frac{\partial}{\partial \rho} \right] = \left[\frac{\partial}{\partial \phi}, \frac{\partial^2}{\partial z^2} \right]$$

$$\left[\frac{\partial}{\partial \phi}, \frac{1}{\rho^2} \frac{\partial^2}{\partial \phi^2} \right] = \frac{1}{\rho} \left[\frac{\partial}{\partial \phi}, \frac{\partial^2}{\partial \phi^2} \right] = 0 \Rightarrow [L_z, H] = 0$$

ANALOGAMENTE: $[H, P_z] = 0$

$$\psi_{n,m,k}(s, \phi, z) = f_{n,m}(s) e^{im\phi} e^{ikz}$$

(b)

$\{H, L_z, P_z\}$ FORMAM UM C.O.C.

$$H\psi = E\psi$$

$$L_z\psi = m\hbar\psi$$

$$P_z\psi = \hbar k\psi$$

$$\frac{\hbar}{i} \frac{\partial}{\partial z}$$

$$P_z e^{ikz} = \hbar k e^{ikz}$$

$$\frac{\hbar}{i} \frac{\partial}{\partial \phi}$$

$$L_z e^{im\phi} = m\hbar e^{im\phi}$$

É RAZOÁVEL CHUTAR A FORMA SEPARÁVEL:

$$\psi_{n,m,k}(s, \phi, z) = f_{n,m}(s) e^{im\phi} e^{ikz}$$

$$\left[-\frac{\hbar^2}{2\mu} \left(\frac{\partial^2}{\partial s^2} + \frac{1}{s} \frac{\partial}{\partial s} + \frac{1}{s^2} \frac{\partial^2}{\partial \phi^2} + \frac{\partial^2}{\partial z^2} \right) + V(s) \right] \psi_{n,m,k} =$$

$$= \left[-\frac{\hbar^2}{2\mu} \left(\frac{\partial^2}{\partial s^2} + \frac{1}{s} \frac{\partial}{\partial s} - \frac{m^2}{s^2} - k^2 \right) + V(s) \right] f e^{im\phi} e^{ikz}$$

$$= E f e^{im\phi} e^{ikz}$$

$$\Rightarrow \left[-\frac{\hbar^2}{2\mu} \left(\frac{\partial^2}{\partial s^2} + \frac{1}{s} \frac{\partial}{\partial s} - \frac{m^2}{s^2} - k^2 \right) + V(s) \right] f_{n,m}(s) = E f_{n,m}(s)$$

$$\left[-\frac{\hbar^2}{2\mu} \left(\frac{\partial^2}{\partial s^2} + \frac{1}{s} \frac{\partial}{\partial s} - \frac{m^2}{s^2} \right) + V(s) \right] f_{n,m}(s) = \underbrace{(E - \frac{\hbar^2 k^2}{2\mu})}_{E'} f_{n,m}(s)$$

4)

$$\psi(\vec{r}, 0) = -A (x+iy) e^{-r/2a_0}$$

$$\psi_{n,\ell,m}(r,\theta,\phi) = R_{n,\ell}(r) Y_{\ell,m}(\theta,\phi)$$

$$x = r \sin\theta \cos\phi$$

$$y = r \sin\theta \sin\phi$$

$$B = -\sqrt{\frac{8\pi}{3}}$$

$$x+iy = r \sin\theta (\cos\phi + i \sin\phi) = r \underbrace{\sin\theta e^{i\phi}}_{B Y_{1,1}(\theta,\phi)}$$

$$\psi(\vec{r}, 0) = -A \times B r Y_{1,1}(\theta,\phi) e^{-r/2a_0}$$

$$= \sqrt{\frac{8\pi}{3}} A \underbrace{(r e^{-r/2a_0})}_{\propto R_{n,\ell}(r)} Y_{1,1}(\theta,\phi)$$

DE (C-39c) DO LIVRO: $R_{n,\ell}(r) = \frac{1}{(2a_0)^{3/2}} \frac{1}{\sqrt{3}} \frac{r}{a_0} e^{-r/2a_0}$

$$\Rightarrow \psi(\vec{r}, 0) = K R_{n,\ell}(r) Y_{1,1}(\theta,\phi)$$

$L^2 \rightarrow 2(2+1)\hbar^2$
 $L \rightarrow E$ É AUTO-FUNÇÃO COM AUTO-VALOR $2\hbar^2$

$L_z \rightarrow E$ " " " "

NORMALIZAÇÃO: $\int |\psi|^2 d\tau = 1$

$$\Rightarrow \underbrace{\int_0^\infty r^2 dr |R_{n,\ell}(r)|^2}_{1} \underbrace{\int_0^\pi \sin\theta d\theta \int_0^{2\pi} d\phi |Y_{\ell,m}(\theta,\phi)|^2}_{1} = 1$$