

FI 008 – Eletrodinâmica I

1º Semestre de 2021

30/03/2021

Aula 5

Magnetostática

Aula passada

$$\nabla \cdot \mathbf{B} = 0 \iff \mathbf{B} = \nabla \times \mathbf{A} \quad (1)$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J} \quad (2)$$

Levando (1) na (2):

$$\nabla \times \mathbf{B} = \nabla \times (\nabla \times \mathbf{A}) = \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = \mu_0 \mathbf{J}$$

Mas a Eq. (1) só nos dá o rotacional de \mathbf{A} .

Seu divergente continua indeterminado.

O teorema de Helmholtz diz que um campo vetorial só fica bem determinado **se dermos seu rot e div.**

Aula passada

Essa indeterminação de \mathbf{A} fica clara, quando adicionamos a ele o gradiente de uma função escalar Λ qualquer:

$$\mathbf{A}' = \mathbf{A} + \nabla\Lambda \Rightarrow \nabla \times \mathbf{A} = \nabla \times \mathbf{A}' \quad (3)$$

$$\left. \begin{array}{l} \mathbf{B} = \nabla \times \mathbf{A} \\ \mathbf{B}' = \nabla \times \mathbf{A}' \end{array} \right\} \Rightarrow \mathbf{B} = \mathbf{B}'$$

A transformação (3) de \mathbf{A} para \mathbf{A}' é chamada de transformação de calibre (ou “gauge”). A invariância de \mathbf{B} por essa transformação é chamada de invariância de calibre (ou “gauge”). Dizemos que a magnetostática é invariante por transformações de calibre (ou “gauge”).

Aula passada

Podemos usar a liberdade de calibre para escolher o **divergente de \mathbf{A} igual a zero** na equação:

$$\nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = \mu_0 \mathbf{J}$$

donde: $\nabla \cdot \mathbf{A} = 0 \Rightarrow \boxed{\nabla^2 \mathbf{A} = -\mu_0 \mathbf{J}}$

Cada componente dessa equação é uma **eq. de Poisson**:

$$\left. \begin{aligned} A_x(\mathbf{x}) &= \frac{\mu_0}{4\pi} \int_{T.E.} \frac{J_x(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} d^3 x' \\ A_y(\mathbf{x}) &= \frac{\mu_0}{4\pi} \int_{T.E.} \frac{J_y(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} d^3 x' \\ A_z(\mathbf{x}) &= \frac{\mu_0}{4\pi} \int_{T.E.} \frac{J_z(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} d^3 x' \end{aligned} \right\} \Rightarrow \boxed{\mathbf{A}(\mathbf{x}) = \frac{\mu_0}{4\pi} \int_{T.E.} \frac{\mathbf{J}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} d^3 x'}$$

Solução geral da magnetostática

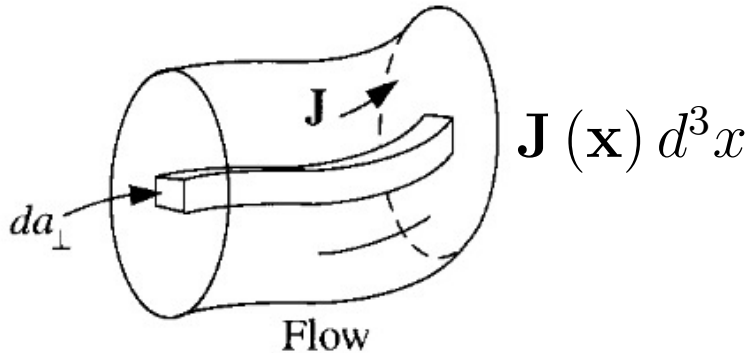
Aula passada

Uma vez obtido \mathbf{A} , podemos achar \mathbf{B} :

$$\mathbf{B}(\mathbf{x}) = \frac{\mu_0}{4\pi} \nabla \times \int_{T.E.} \frac{\mathbf{J}(\mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|} d^3x'$$

$$\mathbf{B}(\mathbf{x}) = \frac{\mu_0}{4\pi} \int_{T.E.} \mathbf{J}(\mathbf{x}') \times \frac{(\mathbf{x} - \mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|^3} d^3x' \quad (\text{Lei de Biot-Savart})$$

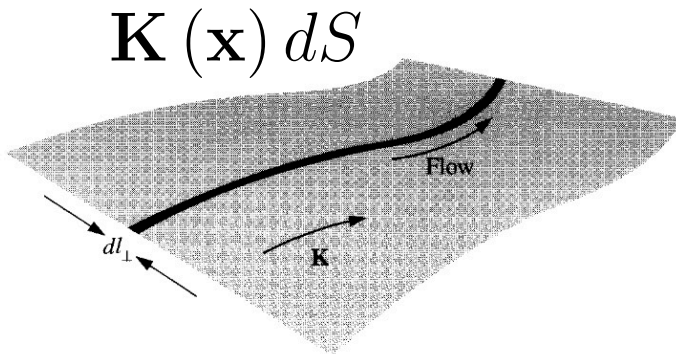
Elementos de corrente



$$\mathbf{A}(\mathbf{x}) = \frac{\mu_0}{4\pi} \int_{T.E.} \frac{\mathbf{J}(\mathbf{x}') d^3x'}{|\mathbf{x} - \mathbf{x}'|}$$

$$\mathbf{B}(\mathbf{x}) = \frac{\mu_0}{4\pi} \int_{T.E.} [\mathbf{J}(\mathbf{x}') d^3x'] \times \frac{(\mathbf{x} - \mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|^3}$$

Correntes superficiais:

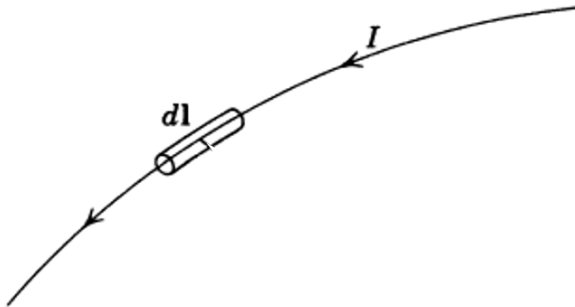


$$\mathbf{A}(\mathbf{x}) = \frac{\mu_0}{4\pi} \int_{T.E.} \frac{\mathbf{K}(\mathbf{x}') dS'}{|\mathbf{x} - \mathbf{x}'|}$$

$$\mathbf{B}(\mathbf{x}) = \frac{\mu_0}{4\pi} \int_{T.E.} [\mathbf{K}(\mathbf{x}') dS'] \times \frac{(\mathbf{x} - \mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|^3}$$

Elementos de corriente

Corrientes lineales (fios):



$$\mathbf{A}(\mathbf{x}) = \frac{\mu_0 I}{4\pi} \int_{T.E.} \frac{d\mathbf{l}'}{|\mathbf{x} - \mathbf{x}'|}$$

$$\mathbf{B}(\mathbf{x}) = \frac{\mu_0 I}{4\pi} \int_{T.E.} d\mathbf{l}' \times \frac{(\mathbf{x} - \mathbf{x}')}{|\mathbf{x} - \mathbf{x}'|^3}$$

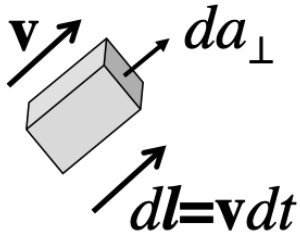
$$\mathbf{J}(\mathbf{x}) d^3x \sim \mathbf{K}(\mathbf{x}) dS \sim I d\mathbf{l}$$

Força de Lorentz sobre correntes

Força magnética sobre elementos de carga:

$$\left. \begin{aligned} \mathbf{F} &= q\mathbf{v} \times \mathbf{B} \\ dq\mathbf{v} &= \rho(\mathbf{x}) \mathbf{v} d^3x \end{aligned} \right\} \Rightarrow d\mathbf{F} = dq\mathbf{v} \times \mathbf{B} = \underbrace{\rho(\mathbf{x}) \mathbf{v}}_{\vec{J}} \times \mathbf{B} d^3x$$

Suponha que um elemento de área (da_{\perp}) é normal à velocidade local da corrente. No intervalo dt , ele varre um volume dV : $dV = dl da_{\perp} = v dt da_{\perp}$

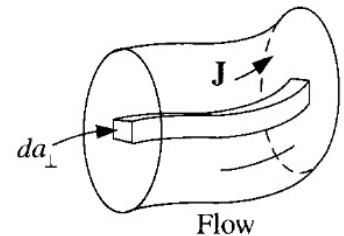


$$\rho dV = \rho v dt da_{\perp} = dq$$

$$J da_{\perp} = I = \frac{dq}{dt}$$

$$J = \frac{dq}{da_{\perp} dt} = \frac{\rho v dt da_{\perp}}{da_{\perp} dt} \Rightarrow J = \rho v \Rightarrow \boxed{\vec{J} = \rho \vec{v}}$$

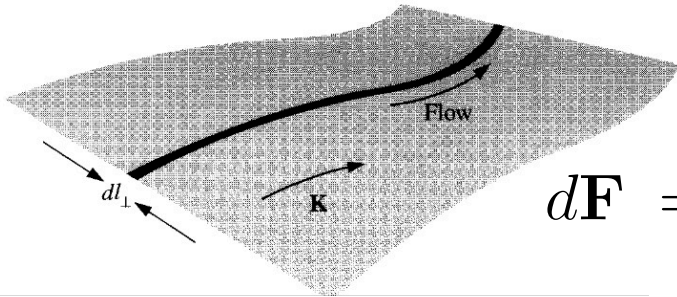
$$d\vec{F} = \vec{J} \times \vec{B} d^3x$$



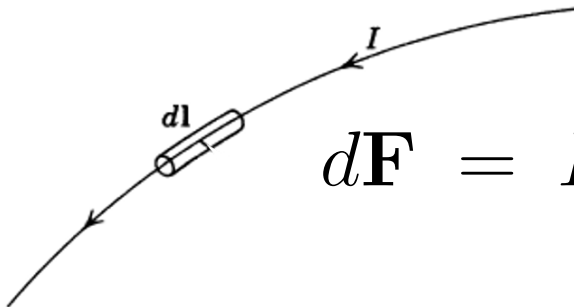
Força de Lorentz sobre correntes

$$d\mathbf{F} = \mathbf{J} \times \mathbf{B} d^3x$$

$$\mathbf{J}(\mathbf{x}) d^3x \sim \mathbf{K}(\mathbf{x}) dS \sim I d\mathbf{l}$$



$$d\mathbf{F} = \mathbf{K} \times \mathbf{B} dS$$



$$d\mathbf{F} = I d\mathbf{l} \times \mathbf{B}$$

Força total: integrar

$$\vec{F} = \int d\vec{F} = \int_{T.E.} \vec{J} \times \vec{B} d^3x$$

$$\vec{F} = \int_{T.E.} \vec{K} \times \vec{B} dS$$

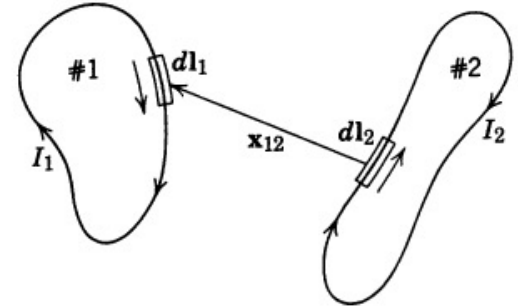
$$\vec{F} = \int_{T.E.} I d\vec{l} \times \vec{B}$$

Força entre 2 circuitos de corrente

$$\mathbf{F}_{2 \rightarrow 1} = \int_{C_1} I_1 d\mathbf{l}_1 \times \mathbf{B}_2(\mathbf{x}_1) = \frac{\mu_0 I_1 I_2}{4\pi} \int_{C_1} d\mathbf{l}_1 \times \left[\int_{C_2} \frac{d\mathbf{l}_2 \times (\mathbf{x}_1 - \mathbf{x}_2)}{|\mathbf{x}_1 - \mathbf{x}_2|^3} \right]$$

$$d\vec{\ell}_1 \times [d\vec{\ell}_2 \times (\underbrace{\mathbf{x}_1 - \mathbf{x}_2}_{\vec{x}_{12}})] =$$

$$= (d\vec{\ell}_1 \cdot \vec{x}_{12}) d\vec{\ell}_2 - (d\vec{\ell}_1 \cdot d\vec{\ell}_2) \vec{x}_{12}$$

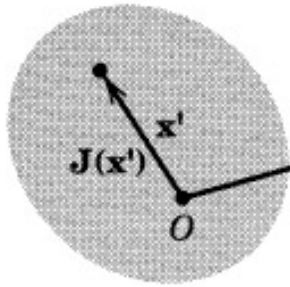


NAS NOTAS EU PROVO QUE A CONTRIBUIÇÃO DO 1º TERMO SE ANULA.

$$\vec{F}_{2 \rightarrow 1} = - \frac{\mu_0 I_1 I_2}{4\pi} \iint_{C_1, C_2} \frac{(d\vec{\ell}_1 \cdot d\vec{\ell}_2) (\vec{x}_1 - \vec{x}_2)}{|\vec{x}_1 - \vec{x}_2|^3} = - \vec{F}_{1 \rightarrow 2}$$

3ª LEI DE NEWTON

Expansão multipolar



$$\vec{A}(\vec{x}) = \frac{\mu_0}{4\pi} \int_{T.E.} \frac{\vec{J}(\vec{x}') d^3x'}{|\vec{x} - \vec{x}'|}$$

DESCRIÇÃO COMPLETA REQUER HARMÔNICOS VETORIAIS, QUE NÃO FAZEMOS.

$$\frac{1}{|\vec{x} - \vec{x}'|} \xrightarrow{|\vec{x}'| \ll |\vec{x}|} = \frac{1}{r} + \frac{\vec{x} \cdot \vec{x}'}{r^3} + O\left(\frac{r'^2}{r^4}\right)$$

$$\vec{A}(\vec{x}) \approx \frac{\mu_0}{4\pi} \left[\underbrace{\frac{1}{r} \int_{T.E.} \vec{J}(\vec{x}') d^3x'}_{1^\circ \text{ TERMO}} + \frac{1}{r^3} \underbrace{\int_{T.E.} (\vec{x} \cdot \vec{x}') \vec{J}(\vec{x}') d^3x'}_{2^\circ \text{ TERMO}} \right]$$

$$\text{SE } \int \vec{J} d^3x' = I d\vec{Q}'$$

$$\Rightarrow \int_{c_i} I d\vec{Q}' = 0$$

Expansão multipolar

$$\nabla' \cdot (x'_i \mathbf{J}) = x'_i \nabla' \cdot \mathbf{J} + J_i \quad (i = 1, 2, 3) \quad x'_i = x', y', z'$$

$$\nabla' (x'_i) = \hat{x}'_i \quad \hat{x}'_i = \nabla' \cdot \mathbf{J}_i$$

INTEGRO EM TODO O ESPAÇO:

$$\int_{T.E.} \nabla' \cdot (x'_i \vec{J}) d^3x' = \int_{S_\infty} (x'_i \vec{J}) \cdot \hat{n}'_i dS' = 0 \quad \text{CORRENTE LOCALIZADA}$$

$$0 = \int_{T.E.} x'_i (\nabla' \cdot \vec{J}) d^3x' + \int_{T.E.} J_i d^3x' \Rightarrow \int_{T.E.} \vec{J} d^3x' = 0$$

CORRENTE ESTACIONÁRIA

TERMO DE MONOPÓLO MAGNÉTICO É IDENTICAMENTE NULO.

Expansão multipolar

SOMA IMPLÍCITA SOBRE i

$$x_i \int_{T.E.} x'_i \mathbf{J}(\mathbf{x}') d^3x' = -\frac{1}{2} \left[\mathbf{x} \times \int \mathbf{x}' \times \mathbf{J}(\mathbf{x}') d^3x' \right] \quad (\text{ver dedução nas notas})$$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \left(\frac{-1}{r^3} \right) \vec{x} \times \left[\frac{1}{2} \int \vec{x}' \times \vec{J}(\vec{r}') d^3x' \right]$$

MOMENTO DE DIPOLO MAGNÉTICO DA
DISTRIBUIÇÃO $\vec{J}(\vec{r}') \Rightarrow \vec{m}$

$$\vec{A}(\vec{r}) = \frac{\mu_0}{4\pi} \frac{\vec{m} \times \vec{x}}{r^3}$$

COMPARE COM $\vec{\Phi}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{\vec{p} \cdot \vec{x}}{r^3}$

$$\vec{B} = \vec{\nabla} \times \vec{A}$$

Expansão multipolar

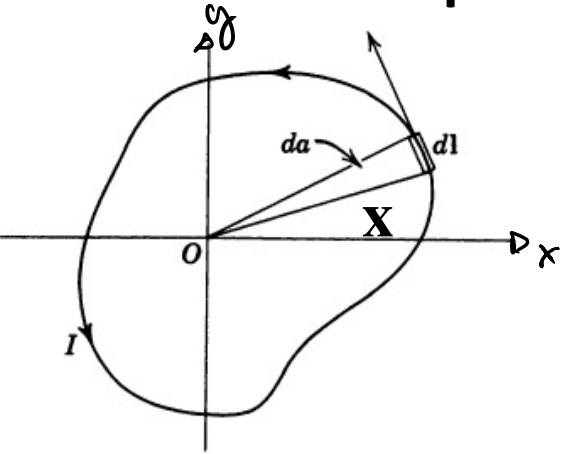
Campos de dipolo magnético:

$$\mathbf{A}(\mathbf{x}) \approx \frac{\mu_0}{4\pi} \frac{\mathbf{m} \times \mathbf{x}}{r^3},$$

$$\mathbf{B}(\mathbf{x}) \approx \frac{\mu_0}{4\pi} \left[\frac{3(\mathbf{m} \cdot \hat{\mathbf{n}}) \hat{\mathbf{n}} - \mathbf{m}}{r^3} \right], \quad \hat{\mathbf{n}} = \hat{\mathbf{r}} = \frac{\mathbf{x}}{r}.$$

Dipolo magnético de um circuito plano de corrente

$$\mathbf{m} = \frac{I}{2} \oint \mathbf{x} \times d\mathbf{l}$$



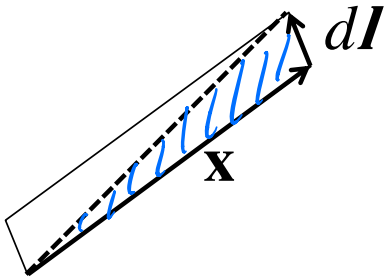
$$\vec{x} \times d\vec{l} \parallel \hat{z}$$

$|\vec{x} \times d\vec{l}| = \text{ÁREA DO PARALELOGRAMO}$

DEFINIDO NA FIGURA AO LADO

$= 2 \text{ ÁREA DO TRIÂNGULO}$

HACHURADO



$$\vec{m} = I \hat{z} \int dA = IA \hat{z}$$

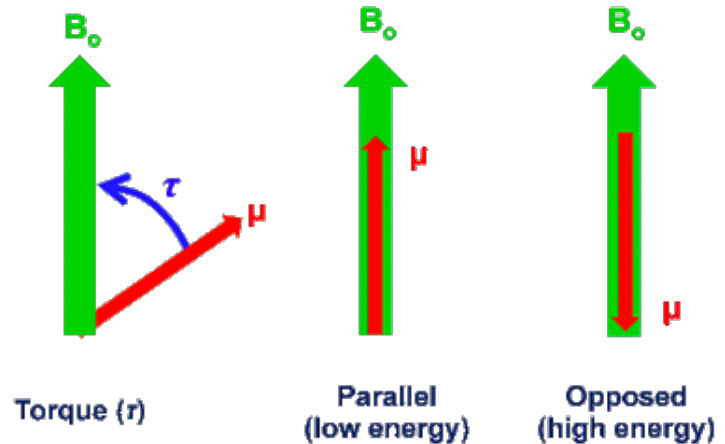
$A = \text{ÁREA CUJA BORDA É O CIRCUITO}$

$$\vec{m} = IA \hat{z}$$

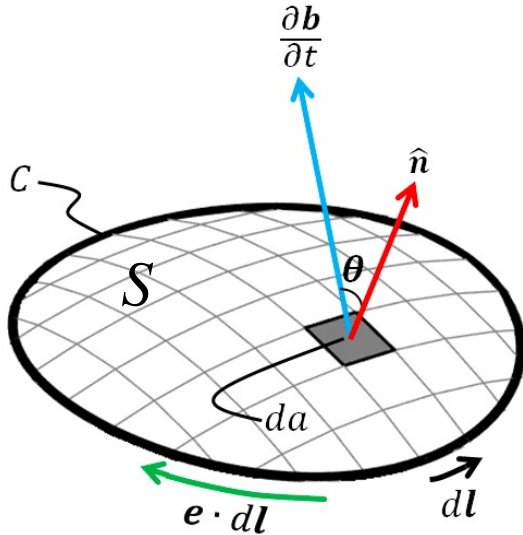
Energia de (e torque sobre) um dipolo magnético num campo externo

$$\boldsymbol{\tau} = \mathbf{m} \times \mathbf{B}_{\text{ext}}$$

$$W = -\mathbf{m} \cdot \mathbf{B}_{\text{ext}}$$



Lei de indução de Faraday



$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

FORMA INTEGRAL:

$$\int_S (\nabla \times \mathbf{E}) \cdot \hat{n} \, dS = - \int_S \left(\frac{\partial \mathbf{B}}{\partial t} \right) \cdot \hat{n} \, dS$$

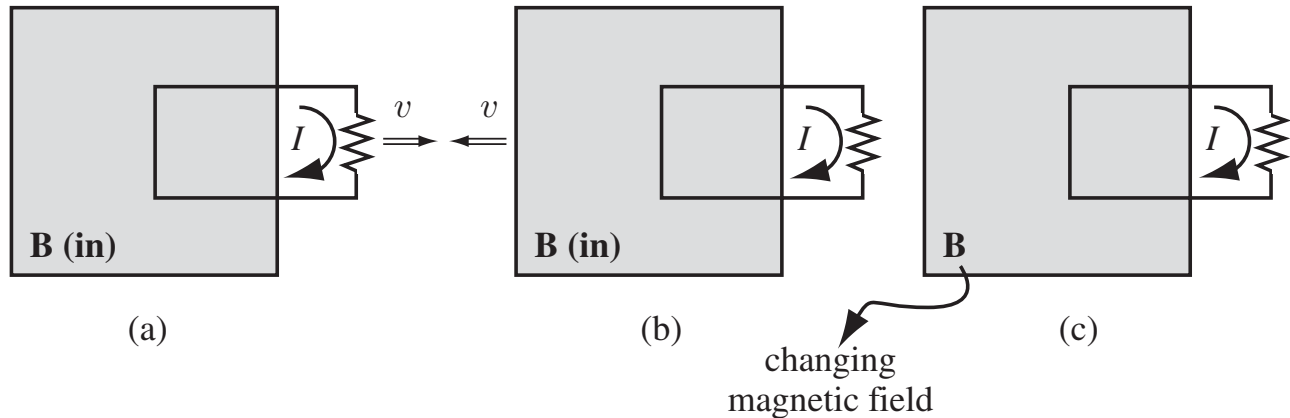
TEOREMA DE STOKES:

$$\mathcal{E} = \oint_{C(s)} \vec{E} \cdot d\vec{\alpha} = - \frac{d}{dt} \left[\underbrace{\int_S \vec{B} \cdot \hat{n} \, dS}_{\Phi_B(s)} \right] = - \frac{d\Phi_B(s)}{dt}$$

LEI DO FLUXO

\mathcal{E} = FORÇA ELETRICADOTRIZ

Lei do fluxo



(a) O circuito **não** está fixo no espaço. A força eletromotriz é consequência da **força magnética** (Lorentz) sobre as cargas.

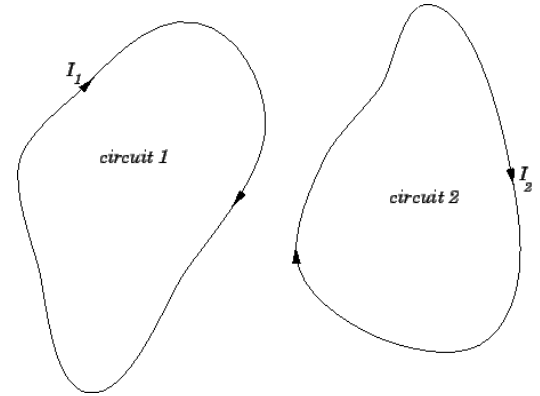
(b) e (c) O circuito está parado. A força eletromotriz vem da **lei de indução de Faraday**.

(a), (b) e (c) A **lei do fluxo** é sempre válida.

$$\varepsilon = - \frac{d\Phi_B}{dt}$$

Energia magnética

Trabalho realizado adiabaticamente
 contra as forças ~~externas~~ ^{ELETROMAGNÉTICAS} para
 estabelecer uma configuração de
 correntes.



$$\begin{aligned} \frac{d(\delta W)}{dt} &= d \int_{\text{ext}} \vec{F} \cdot d\vec{r} = -dq (\vec{E} + \vec{v} \times \vec{B}) \cdot \vec{v} & (\vec{v} \times \vec{B}) \cdot \vec{v} &= 0 \\ &= -dq \vec{E} \cdot \vec{v} \\ &= -\int \vec{E} \cdot \vec{j} d^3x = -\int \vec{j} \cdot \vec{E} d^3x \end{aligned}$$

$$\Rightarrow \frac{dW}{dt} = \int_{T.E.} \vec{j} \cdot \vec{E} d^3x = -\frac{1}{\mu_0} \int (\vec{\nabla} \times \vec{B}) \cdot \vec{E} d^3x$$

$$\frac{dW}{dt} = -\frac{1}{\mu_0} \int_{T.E.} (\nabla \times \vec{B}) \cdot \vec{E} \, d^3x$$

$$\nabla \cdot (\mathbf{E} \times \mathbf{B}) = (\nabla \times \mathbf{E}) \cdot \mathbf{B} - (\nabla \times \mathbf{B}) \cdot \mathbf{E}$$

$$= \frac{1}{\mu_0} \left[\int_{T.E.} \nabla \cdot (\vec{E} \times \vec{B}) \, d^3x - \int_{T.E.} \vec{B} \cdot (\nabla \times \vec{E}) \, d^3x \right] = (*)$$

T. GAUSS

$\int_{S_\infty} (\vec{E} \times \vec{B}) \cdot \hat{n} \, dS \rightarrow 0$: PARA DISTRIBUIÇÕES LOCALIZADAS DE CARGAS E CORRENTES!

$$\vec{E} \sim \frac{1}{r^2} \quad \vec{B} \sim \frac{1}{r^2}$$

$$\vec{E} \times \vec{B} \sim \frac{1}{r^4} \quad \int dS \sim R^2$$

$$(*) = +\frac{1}{\mu_0} \int_{T.E.} \vec{B} \cdot \frac{\partial \vec{B}}{\partial t} \, d^3x = \frac{1}{\mu_0} \int_{T.E.} \frac{\partial}{\partial t} \left[\frac{\vec{B} \cdot \vec{B}}{2} \right] \, d^3x =$$

$$\frac{dW}{dt} = \frac{1}{2\mu_0} \frac{d}{dt} \left[\int_{T.E.} B^2 \, d^3x \right] \Rightarrow$$

$$W = \int_{T.E.} \frac{B^2}{2\mu_0} \, d^3x$$

COMPARE COM

$$W = \frac{\epsilon_0}{2} \int_{T.E.} E^2 \, d^3x$$

$$\nabla \cdot (\mathbf{A} \times \mathbf{B}) = (\nabla \times \mathbf{A}) \cdot \mathbf{B} - (\nabla \times \mathbf{B}) \cdot \mathbf{A}$$

$$W = \frac{1}{2\mu_0} \int_{\text{T.E.}} \vec{B} \cdot \vec{B} \, d^3x$$

$$= \frac{1}{2\mu_0} \int_{\text{T.E.}} [(\nabla \times \vec{A}) \cdot \vec{B}] \, d^3x = \frac{1}{2\mu_0} \left[\int_{\text{T.E.}} \nabla \cdot (\vec{A} \times \vec{B}) \, d^3x + \int_{\text{T.E.}} \vec{A} \cdot (\nabla \times \vec{B}) \, d^3x \right]$$

$$\vec{A} \sim \frac{1}{r^2} \quad \nabla \times \vec{B} \sim \frac{1}{r^3}$$

$$\vec{B} \sim \frac{1}{r^3}$$

$$\int_{S_\infty} (\vec{A} \times \vec{B}) \cdot \hat{n} \, dS \rightarrow 0$$

$$W = \frac{1}{2\mu_0} \int_{\text{T.E.}} \vec{A} \cdot \underbrace{(\nabla \times \vec{B})}_{\mu_0 \vec{J}} \, d^3x = \frac{1}{2} \int_{\text{T.E.}} \vec{A} \cdot \vec{J} \, d^3x$$

COMPARE COM: $W = \frac{1}{2} \int_{\text{T.E.}} \mathcal{J} \Phi \, d^3x$

$$W = \frac{1}{2} \int \vec{A}(\vec{x}) \cdot \vec{J}(\vec{x}) d^3x$$

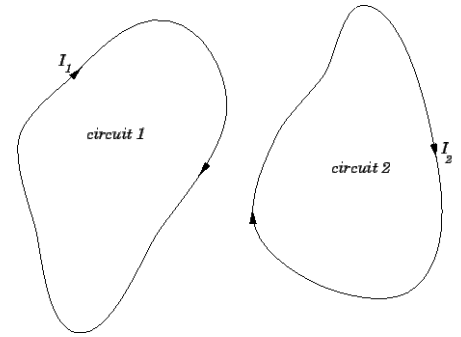
$$W = \frac{\mu_0}{8\pi} \int \frac{\vec{J}(\vec{x}) \cdot \vec{J}(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3x d^3x'$$

COMPARE COM:

$$W = \frac{1}{8\pi\epsilon_0} \int \frac{\rho(\vec{x}) \rho(\vec{x}')}{|\vec{x} - \vec{x}'|} d^3x d^3x'$$

$$\mathbf{A}(\mathbf{x}) = \frac{\mu_0}{4\pi} \int_{T.E.} \frac{\mathbf{J}(\mathbf{x}') d^3x'}{|\mathbf{x} - \mathbf{x}'|}$$

Indutâncias



$$W = \frac{\mu_0}{8\pi} \int_{T.E.} \frac{\mathbf{J}(\mathbf{x}) \cdot \mathbf{J}(\mathbf{x}') d^3x d^3x'}{|\mathbf{x} - \mathbf{x}'|}$$

N circuitos de correntes: $\mathbf{J}(\mathbf{x}) = \sum_{i=1}^N \mathbf{J}_i(\mathbf{x})$

$$W = \left[\frac{\mu_0}{8\pi} \sum_{i=1}^N \int_{T.E.} \frac{\mathbf{J}_i(\mathbf{x}) \cdot \mathbf{J}_i(\mathbf{x}') d^3x d^3x'}{|\mathbf{x} - \mathbf{x}'|} + \frac{\mu_0}{8\pi} \sum_{\substack{i,j=1 \\ i \neq j}}^N \int_{T.E.} \frac{\mathbf{J}_i(\mathbf{x}) \cdot \mathbf{J}_j(\mathbf{x}') d^3x d^3x'}{|\mathbf{x} - \mathbf{x}'|} \right]$$

Como $J \sim I$: $M_{ij} = \frac{\mu_0}{4\pi} \frac{1}{I_i I_j} \int_{T.E.} \frac{\mathbf{J}_i(\mathbf{x}) \cdot \mathbf{J}_j(\mathbf{x}') d^3x d^3x'}{|\mathbf{x} - \mathbf{x}'|} = M_{ji}$

$$L_i = \frac{\mu_0}{4\pi} \frac{1}{I_i^2} \int_{T.E.} \frac{\mathbf{J}_i(\mathbf{x}) \cdot \mathbf{J}_i(\mathbf{x}') d^3x d^3x'}{|\mathbf{x} - \mathbf{x}'|}$$

$$W = \left[\frac{1}{2} \sum_{i=1}^N L_i I_i^2 + \sum_{i,j=1, i < j}^N M_{ij} I_i I_j \right]$$

Indutâncias mútuas

Auto-indutâncias

Puramente geométricas

$$M_{ij} = \frac{\mu_0}{4\pi} \frac{1}{I_i I_j} \int_{T.E.} \frac{\mathbf{J}_i(\mathbf{x}) \cdot \mathbf{J}_j(\mathbf{x}') d^3x d^3x'}{|\mathbf{x} - \mathbf{x}'|},$$

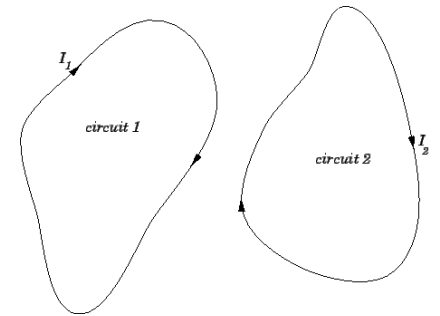
Separando o potencial vetor devido ao circuito j :

$$\mathbf{A}_j(\mathbf{x}) = \frac{\mu_0}{4\pi} \int_{T.E.} \frac{\mathbf{J}_j(\mathbf{x}') d^3x'}{|\mathbf{x} - \mathbf{x}'|}$$

$$M_{ij} = \frac{1}{I_i I_j} \int_{T.E.} \mathbf{J}_i(\mathbf{x}) \cdot \mathbf{A}_j(\mathbf{x}) d^3x \quad (\mathbf{J}_i d^3x \rightarrow I_i d\mathbf{l}_i)$$

$$= \frac{1}{I_i I_j} \int I_i d\vec{\ell}_i \cdot \vec{A}_j(\vec{x})$$

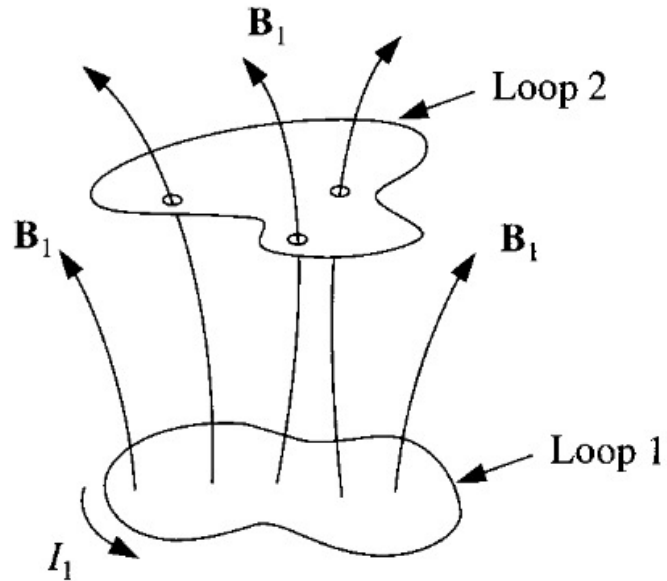
$$= \frac{1}{I_j} \int_{C_i} \vec{A}_j \cdot d\vec{\ell}_i = \frac{1}{I_j} \int_{S(C_i)} (\nabla \times \vec{A}_j) \cdot d\vec{S}_i$$



$$M_{ij} = \frac{1}{I_j} \Phi_B(j \rightarrow i) = \frac{1}{I_i} \Phi_B(i \rightarrow j)$$

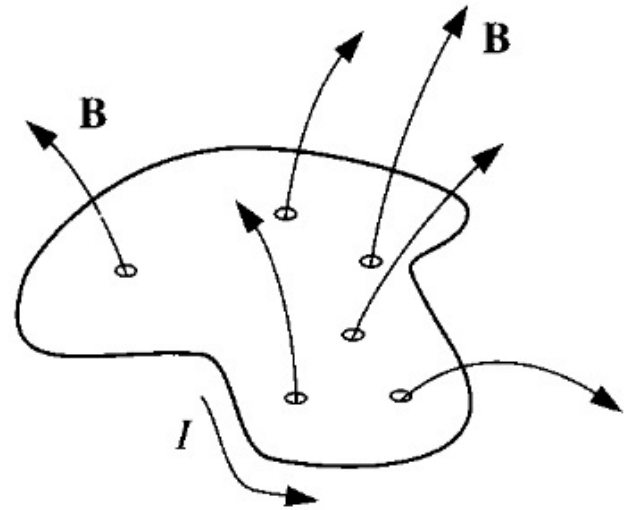
$$L_i = \frac{1}{I_i} \Phi_B(i \rightarrow i)$$

Indutância mútua



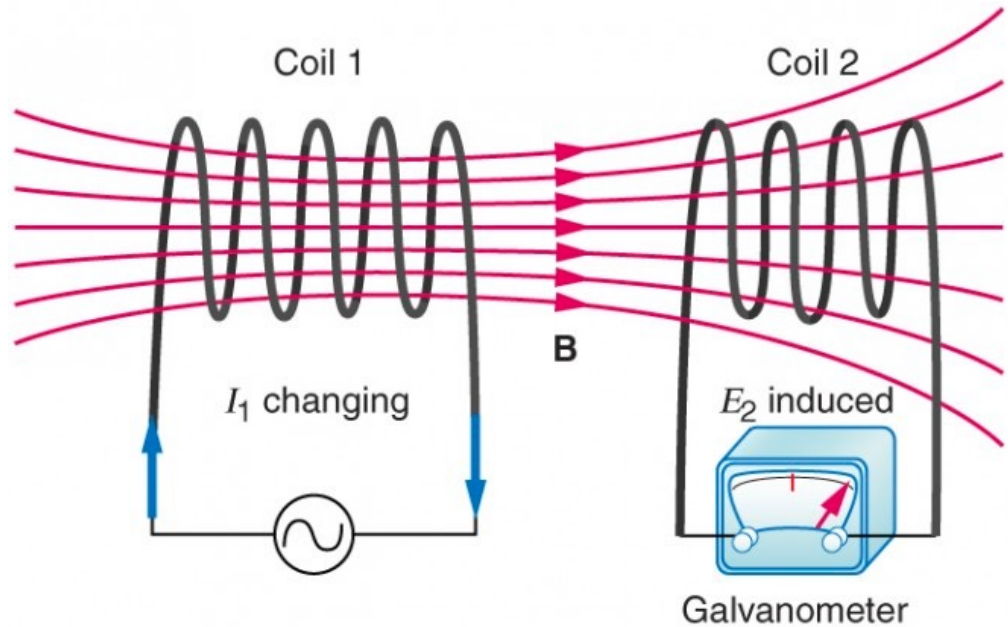
$$\Phi_B (j \rightarrow i) = M_{ij} I_j$$

Auto-indutância



$$\Phi_B (i \rightarrow i) = L_i I_i$$

Indutância



$$\Phi_B (1 \rightarrow 2) = M_{12} I_1$$

$$\Rightarrow \frac{d\Phi_B (1 \rightarrow 2)}{dt} = M_{12} \frac{dI_1}{dt}$$

$$-\mathcal{E}_2$$

$$\Rightarrow \mathcal{E}_2 = -M_{12} \frac{dI_1}{dt}$$

$$\mathcal{E}_1 = -L_1 \frac{dI_1}{dt}$$